

# Errata do livro: O Método de elementos finitos aplicado à Mecânica dos Sólidos

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September 27, 2020

A seguir são indicados erros tipográficos envolvendo apenas as equações. Não são indicados erros de ortografia.

Capítulo	Página	eq. ou figura	Atual	Corrigido
4	67	(4.24)	$\begin{Bmatrix} \sigma_{11} \\ \sigma_{22} \\ \sigma_{33} \end{Bmatrix} = \dots \begin{bmatrix} 1 & \frac{1}{(1-\nu)} & 0 \\ \frac{1}{(1-\nu)} & 1 & 0 \\ 0 & 0 & \frac{1-2\nu}{2(1-\nu)} \end{bmatrix}$	$\begin{Bmatrix} \sigma_{11} \\ \sigma_{22} \\ \sigma_{33} \end{Bmatrix} = \dots \begin{bmatrix} 1 & \frac{\nu}{(1-\nu)} & 0 \\ \frac{\nu}{(1-\nu)} & 1 & 0 \\ 0 & 0 & \frac{1-2\nu}{2(1-\nu)} \end{bmatrix}$
7	178	Exercício 7.3c	$L_2(x) = \underbrace{4x}_1 - x$	$L_2(x) = \underbrace{4x(1-x)}_1$
8	185	(8.31)	$\begin{Bmatrix} \sigma_x \\ \sigma_y \\ \sigma_{xy} \end{Bmatrix} = \dots \begin{bmatrix} \nu & \frac{1}{(1-\nu)} & 0 \\ \frac{1}{(1-\nu)} & \nu & 0 \\ 0 & 0 & \frac{1-2\nu}{2(1-\nu)} \end{bmatrix}$	$\begin{Bmatrix} \sigma_x \\ \sigma_y \\ \sigma_{xy} \end{Bmatrix} = \dots \begin{bmatrix} 1 & \frac{\nu}{(1-\nu)} & 0 \\ \frac{\nu}{(1-\nu)} & 1 & 0 \\ 0 & 0 & \frac{1-2\nu}{2(1-\nu)} \end{bmatrix}$
13	351	Fig 13.7 (b)	$\psi_3^2$	$\psi_2^2$
16	443	(16.26)	$\begin{Bmatrix} \varepsilon_x \\ \varepsilon_y \\ \gamma_{xy}/2 \end{Bmatrix} = \mathbf{T}^{-1} \begin{Bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \underbrace{\gamma_{xy}/2} \end{Bmatrix}$	$\begin{Bmatrix} \varepsilon_x \\ \varepsilon_y \\ \gamma_{xy}/2 \end{Bmatrix} = \mathbf{T}^{-1} \begin{Bmatrix} \varepsilon_1 \\ \varepsilon_2 \\ \underbrace{\gamma_{12}/2} \end{Bmatrix}$

Capítulo	Página	eq. ou figura	Atual	Corrigido
16	448	(16.39)	$\mathbf{Q} = \left\{ \begin{array}{c} Q_y \\ Q_x \end{array} \right\} = \sum_{k=1}^N \underbrace{\int_{-H/2}^{H/2}}_k \left\{ \begin{array}{c} \tau_{yz} \\ \tau_{zx} \end{array} \right\}^{l_k} dz$	$\mathbf{Q} = \left\{ \begin{array}{c} Q_y \\ Q_x \end{array} \right\} = \sum_{k=1}^N \underbrace{\int_{z_{k-1}}^{z_k}}_k \left\{ \begin{array}{c} \tau_{yz} \\ \tau_{zx} \end{array} \right\}^{l_k} dz$
16	449	(16.40) <sub>3</sub>	$\mathbf{Q} = \sum_{k=1}^N \left[ \begin{array}{cc} C_{44}^x & C_{45}^x \\ C_{45}^x & C_{55}^x \end{array} \right]^k \left\{ \begin{array}{c} \gamma_{yz} \\ \gamma_{zx} \end{array} \right\}^{l_k} \underbrace{\int_{-H/2}^{H/2}}_k dz$	$\mathbf{Q} = \sum_{k=1}^N \left[ \begin{array}{cc} C_{44}^x & C_{45}^x \\ C_{45}^x & C_{55}^x \end{array} \right]^k \left\{ \begin{array}{c} \gamma_{yz} \\ \gamma_{zx} \end{array} \right\}^{l_k} \underbrace{\int_{z_{k-1}}^{z_k}}_k dz$
16	449	(16.42) <sub>3</sub>	$E_{rs} = k_c \underbrace{\sum_{k=1}^N}_{k=1ij} C_{rs}^{x,k} h_k$	$E_{rs} = k_c \underbrace{\sum_{k=1}^N}_{k=1} C_{rs}^{x,k} h_k$
16	448	Fig. 16.6	Numeracao das lâminas: 2-1-...-k-...N	1-2-...-k-...N
16	453	(16.58) <sub>1</sub>	$\underbrace{\left\{ \begin{array}{c} \varepsilon^o \\ \kappa \end{array} \right\}}_h^e = \mathbf{B}_f^e(x, y) \hat{\mathbf{U}}^e$	$\underbrace{\left\{ \begin{array}{c} \hat{\varepsilon}^o \\ \hat{\kappa} \end{array} \right\}}_h^e = \mathbf{B}_f^e(x, y) \hat{\mathbf{U}}^e$
19	511	Exemplo 19.1	Considere a barra do Exemplo 17.11.1...	Considere a barra do Exemplo 18.1...
19	540	Figura 19.11	Na própria figura, $m_2 = m$	$m_2 = 2m$
20	547	Tabela 20.1	Item 12: $\phi_j = \arctan \left\{ \frac{2\zeta_j \Omega}{(1 - \beta_j^2)} \right\}$	$\phi_j = \arctan \left\{ \frac{2\zeta_j \beta_j}{(1 - \beta_j^2)} \right\}$
20	553	Tabela 20.2		Remover itens 12 e 14.
21	562	Tabela	Etapa 4 - ... $m/s$ ...	... $m/s_d$ ...
21	567	(21.39)	$a_4 = \frac{1}{\alpha} - 1$	$a_4 = \frac{\delta}{\alpha} - 1$
21	568	Tabela 21.1	Etapa 2c) Aplicar condições de contorno em $\hat{\mathbf{K}}$ .	Aplicar condições de contorno em $\hat{\mathbf{K}}$ e $\hat{\mathbf{u}}_o$ .